

Slides thanks to

- Martin Henz Aquinas Hobor
- CS 3234: Logic and Formal Systems

Notions of Truth

- Often, it is not enough to distinguish between “true” and “false”.
- We need to consider *modalities* if truth, such as:
 - necessity
 - time
 - knowledge by an agent
- Modal logic constructs a framework using which modalities can be formalized and reasoning methods can be established.

Syntax of Basic Modal Logic

$$\begin{aligned}\phi \quad ::= & \top \mid \perp \mid \boldsymbol{p} \mid (\neg\phi) \mid (\phi \wedge \phi) \\ & \mid (\phi \vee \phi) \mid (\phi \rightarrow \phi) \\ & \mid (\phi \leftrightarrow \phi) \\ & \mid (\Box\phi) \mid (\Diamond\phi)\end{aligned}$$

Kripke Models

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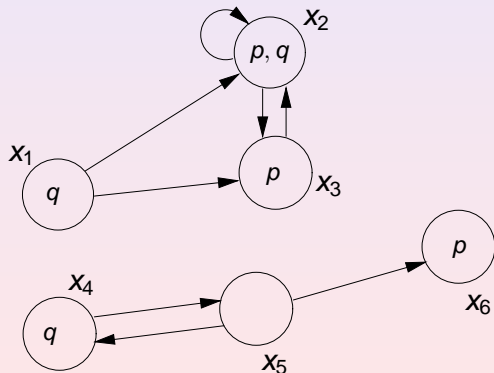
- 1 A W of *worlds*;
- 2 a relation R on W , meaning $R \subseteq W \times W$, called the *accessibility relation*;
- 3 a function $L : W \rightarrow A \rightarrow \{T, F\}$, called *labeling function*.

Example

$$W = \{x_1, x_2, x_3, x_4, x_5, x_6\}$$

$$R = \{(x_1, x_2), (x_1, x_3), (x_2, x_2), (x_2, x_3), (x_3, x_2), (x_4, x_5), (x_5, x_4), (x_5, x_6)\}$$

$$L = \{(x_1, \{q\}), (x_2, \{p, q\}), (x_3, \{p\}), (x_4, \{q\}), (x_5, \{\}), (x_6, \{p\})\}$$



When is a formula true in a possible world?

Definition

Let $\mathcal{M} = (W, R, L)$, $x \in W$, and ϕ a formula in basic modal logic. We define $x \Vdash \phi$ via structural induction:

- $x \Vdash \top$
- $x \not\Vdash \perp$
- $x \Vdash p$ iff $p \in L(x)(p) = T$
- $x \Vdash \neg\phi$ iff $x \not\Vdash \phi$
- $x \Vdash \phi \wedge \psi$ iff $x \Vdash \phi$ and $x \Vdash \psi$
- $x \Vdash \phi \vee \psi$ iff $x \Vdash \phi$ or $x \Vdash \psi$
- ...

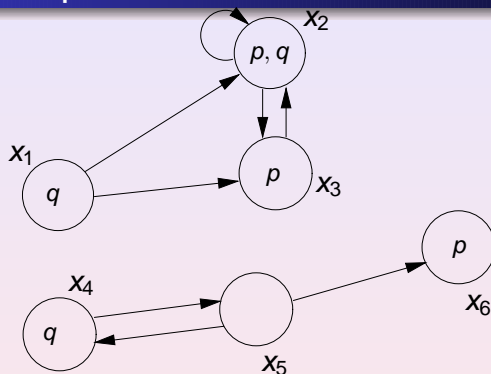
When is a formula true in a possible world?

Definition (continued)

Let $\mathcal{M} = (W, R, L)$, $x \in W$, and ϕ a formula in basic modal logic. We define $x \Vdash \phi$ via structural induction:

- ...
- $x \Vdash \phi \rightarrow \psi$ iff $x \Vdash \psi$, whenever $x \Vdash \phi$
- $x \Vdash \phi \leftrightarrow \psi$ iff ($x \Vdash \phi$ iff $x \Vdash \psi$)
- $x \Vdash \Box\phi$ iff for each $y \in W$ with $R(x, y)$, we have $y \Vdash \phi$
- $x \Vdash \Diamond\phi$ iff there is a $y \in W$ such that $R(x, y)$ and $y \Vdash \phi$.

Example



- $x_1 \Vdash q$
- $x_1 \Vdash \Diamond q$, $x_1 \nVdash \Box q$
- $x_5 \nVdash \Box p$, $x_5 \nVdash \Box q$, $x_5 \nVdash \Box p \vee \Box q$, $x_5 \Vdash \Box(p \vee q)$
- $x_6 \Vdash \Box \phi$ holds for all ϕ , but $x_6 \nVdash \Diamond \phi$

A Range of Modalities

In a particular context $\Box\phi$ could mean:

- It is necessarily true that ϕ
- It will always be true that ϕ
- It ought to be that ϕ
- Agent Q believes that ϕ
- Agent Q knows that ϕ
- After any execution of program P , ϕ holds.

Since $\Diamond\phi \equiv \neg\Box\neg\phi$, we can infer the meaning of \Diamond in each context.

A Range of Modalities

From the meaning of $\Box\phi$, we can conclude the meaning of $\Diamond\phi$, since $\Diamond\phi \equiv \neg\Box\neg\phi$:

$\Box\phi$	$\Diamond\phi$
It is necessarily true that ϕ	It is possibly true that ϕ
It will always be true that ϕ	Sometime in the future ϕ
It ought to be that ϕ	It is permitted to be that ϕ
Agent Q believes that ϕ	ϕ is consistent with Q's beliefs
Agent Q knows that ϕ	For all Q knows, ϕ
After any run of P , ϕ holds.	After some run of P , ϕ holds

Formula Schemes that hold wrt some Modalities

$\Box\phi$	$\Box\phi \rightarrow \phi$	$\Box\phi \rightarrow \Box\Box\phi$	$\Box\phi \rightarrow \Box\Diamond\phi$	$\Box\phi \rightarrow \Box\Box\Box\phi$	$\Box\phi \rightarrow \Box\Diamond\Box\phi$	$\Box\phi \rightarrow \Box(\phi \vee \Box\neg\phi)$	$\Box\phi \rightarrow \Box(\phi \rightarrow \psi) \wedge \Box\phi \rightarrow \Box\psi$	$\Box\phi \rightarrow \Box(\phi \wedge \Diamond\psi) \rightarrow \Box(\phi \wedge \psi)$
It is necessary that ϕ	✓	✓	✓	✓	✓	×	✓	×
It will always be that ϕ	×	✓	×	×	×	×	✓	×
It ought to be that ϕ	×	×	×	✓	✓	×	✓	×
Agent Q believes that ϕ	×	✓	✓	✓	✓	×	✓	×
Agent Q knows that ϕ	✓	✓	✓	✓	✓	×	✓	×
After running P, ϕ	×	×	×	×	×	×	✓	×

Modalities lead to Interpretations of R

 $\Box\phi$
 $R(x, y)$

It is necessarily true that ϕ

y is possible world according to info at x

It will always be true that ϕ

y is a future world of x

It ought to be that ϕ

y is an acceptable world according to the information at x

Agent Q believes that ϕ

y could be the actual world according to Q 's beliefs at x

Agent Q knows that ϕ

y could be the actual world according to Q 's knowledge at x

After any execution of P , ϕ holds

y is a possible resulting state after execution of P at x

Possible Properties of R

- reflexive: for every $w \in W$, we have $R(x, x)$.
- symmetric: for every $x, y \in W$, we have $R(x, y)$ implies $R(y, x)$.
- serial: for every x there is a y such that $R(x, y)$.
- transitive: for every $x, y, z \in W$, we have $R(x, y)$ and $R(y, z)$ imply $R(x, z)$.
- Euclidean: for every $x, y, z \in W$ with $R(x, y)$ and $R(x, z)$, we have $R(y, z)$.
- functional: for each x there is a unique y such that $R(x, y)$.
- linear: for every $x, y, z \in W$ with $R(x, y)$ and $R(x, z)$, we have $R(y, z)$ or $y = z$ or $R(z, y)$.
- total: for every $x, y \in W$, we have $R(x, y)$ and $R(y, x)$.
- equivalence: reflexive, symmetric and transitive.

Reflexivity and Transitivity

Theorem

The following statements are equivalent:

- R is reflexive;
- \mathcal{F} satisfies $\Box\phi \rightarrow \phi$;
- \mathcal{F} satisfies $\Box p \rightarrow p$;

Theorem

The following statements are equivalent:

- R is transitive;
- \mathcal{F} satisfies $\Box\phi \rightarrow \Box\Box\phi$;
- \mathcal{F} satisfies $\Box p \rightarrow \Box\Box p$;

Formula Schemes and Properties of R

name	formula scheme	property of R
T	$\Box\phi \rightarrow \phi$	reflexive
B	$\phi \rightarrow \Box\Diamond\phi$	symmetric
D	$\Box\phi \rightarrow \Diamond\phi$	serial
4	$\Box\phi \rightarrow \Box\Box\phi$	transitive
5	$\Diamond\phi \rightarrow \Box\Diamond\phi$	Euclidean
	$\Box\phi \leftrightarrow \Diamond\phi$	functional
	$\Box(\phi \wedge \Box\phi \rightarrow \psi) \vee \Box(\psi \wedge \Box\psi \rightarrow \phi)$	linear

- 1 Review of Modal Logic
- 2 **Some Modal Logics**
 - K
 - KT45
 - KT4
- 3 Natural Deduction in Modal Logic
- 4 Knowledge in Multi-Agent Systems

Which Formula Schemes to Choose?

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Let \mathcal{L} be a set of formula schemes and $\Gamma \cup \{\psi\}$ a set of formulas of basic modal logic.

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- Let \mathcal{L}_c be the smallest closed superset of \mathcal{L} .

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Let \mathcal{L} be a set of formula schemes and $\Gamma \cup \{\psi\}$ a set of formulas of basic modal logic.

- A set of formula schemes is said to be *closed* iff it contains all substitution instances of its elements.
- Let \mathcal{L}_c be the smallest closed superset of \mathcal{L} .
- Γ entails ψ in \mathcal{L} iff $\Gamma \cup \mathcal{L}_c$ semantically entails ψ . We say $\Gamma \models_{\mathcal{L}} \psi$.

Examples of Modal Logics: K

K is the weakest modal logic, $\mathcal{L} = \emptyset$.

Examples of Modal Logics: KT45

$$\mathcal{L} = \{T, 4, 5\}$$

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- T: Truth: agent Q only knows true things.
- 4: Positive introspection: If Q knows something, he knows that he knows it.
- 5: Negative introspection: If Q doesn't know something, he knows that he doesn't know it.

Explanation of Negative Introspection

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$$\begin{aligned}\Diamond\phi &\rightarrow \Box\Diamond\phi \\ \Diamond\neg\psi &\rightarrow \Box\Diamond\neg\psi\end{aligned}$$

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If Q doesn't know ψ , he knows that he doesn't know ψ .

Correspondence for KT45

Accessibility relations for KT45

KT45 hold if and only if R is reflexive (T), transitive (4) and Euclidean (5).

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Fact on such relations

A relation is reflexive, transitive and Euclidean iff it is reflexive, transitive and symmetric, i.e. iff it is an equivalence relation.

Collapsing Modalities

Theorem

Any sequence of modal operators and negations is KT45 is equivalent to one of the following: \neg , \Box , \Diamond , \neg , $\neg\Box$, and $\neg\Diamond$, where \neg indicates the absence of any negation or modality.

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- $\Box\Box\phi \equiv \Box\phi$

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Examples

- $\Box\Box\phi \equiv \Box\phi$
- $\Diamond\Box\phi \equiv \Diamond\phi$
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Definition

A reflexive and transitive relation is called a *preorder*.

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Any sequence of modal operators and negations is KT4 is equivalent to one of the following:

$\neg, \Box, \Diamond, \Box\Diamond, \Diamond\Box, \Box\Box, \Diamond\Diamond, \neg, \neg\Box, \neg\Diamond, \neg\Box\Diamond, \neg\Diamond\Box, \neg\Box\Diamond\Box,$ and $\neg\Diamond\Box\Diamond$.

Connection to Intuitionistic Logic

Definition

A model of intuitionistic propositional logic is a model $\mathcal{M} = (W, R, L)$ of KT4 such that $R(x, y)$ always implies $L(x)(p) \rightarrow L(y)(p)$.

Satisfaction in Intuitionistic Logic

Definition

We change the definition of $x \Vdash \phi$ as follows:

- $x \Vdash \top$
- $x \nVdash \perp$
- $x \Vdash p$ iff $p \in L(x)$
- $x \Vdash \phi \wedge \psi$ iff $x \Vdash \phi$ and $x \Vdash \psi$
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- $x \Vdash \neg\phi$ **iff** for all y with $R(x, y)$, we have $y \nVdash \phi$
- $x \Vdash \phi \rightarrow \psi$ **iff** for all y with $R(x, y)$, we have $y \Vdash \psi$ whenever we have $y \Vdash \phi$.

Example

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 $L(x)(p) = F$, $L(y)(p) = T$.

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Since

- $x \Vdash \neg \phi$ iff for all y with $R(x, y)$, we have $y \not\Vdash \phi$

we cannot establish $x \Vdash \neg p$.

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Idea

Do not allow “assumptions”, even if they exhaust all possibilities.

- 1 Review of Modal Logic
- 2 Some Modal Logics
- 3 Natural Deduction in Modal Logic**
 - More Boxes
 - Rules
 - Extra Rules
 - Example
- 4 Knowledge in Multi-Agent Systems

Dashed Boxes

Idea

In addition to proof boxes for assumptions, we introduce *blue boxes* that express knowledge about an *arbitrary accessible world*.

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- Whenever $\Box\phi$ occurs in a proof, ϕ may be put into a subsequent blue box.

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Rules about blue boxes

- Whenever $\Box\phi$ occurs in a proof, ϕ may be put into a subsequent blue box.
- Whenever ϕ occurs at the end of a blue box, $\Box\phi$ may be put after that blue box.

Rules for \Box

Introduction of \Box :

$$\frac{\begin{array}{c} \vdots \\ \phi \end{array}}{\Box \phi} [\Box i]$$

Rules for \Box

Elimination of \Box :

$$\frac{\Box\phi}{\boxed{\begin{array}{c} \vdots \\ \phi \\ \vdots \end{array}}} [\Box e]$$

Extra Rules for KT45

$$\frac{\Box\phi}{\phi} [T]$$

$$\frac{\Box\phi}{\Box\Box\phi} [4]$$

$$\frac{\neg\Box\phi}{\Box\neg\Box\phi} [5]$$

Example Proof

$$\vdash_K \Box p \wedge \Box q \rightarrow \Box(p \wedge q)$$

1	$\Box p \wedge \Box q$	assumption
2	$\Box p$	$\wedge e_1$ 1
3	$\Box q$	$\wedge e_2$ 1
4	p	$\Box e$ 2
5	q	$\Box e$ 3
6	$p \wedge q$	$\wedge i$ 4,5
7	$\Box(p \wedge q)$	$\Box i$ 4–6
8	$\Box p \wedge \Box q \rightarrow \Box(p \wedge q)$	$\rightarrow i$ 1–7

- 1 Review of Modal Logic
- 2 Some Modal Logics
- 3 Natural Deduction in Modal Logic
- 4 Knowledge in Multi-Agent Systems**
 - Motivation: The Wise Women Puzzle
 - Modal Logic KT45ⁿ
 - Models of KT45ⁿ
 - Formulation of Wise-Women Puzzle

Wise Women Puzzle

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Answer: No
- Queen asks second wise woman: Do you know the color of your hat.
Answer: No
- Queen asks third wise woman: Do you know the color of your hat?

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Answer: No
- Queen asks second wise woman: Do you know the color of your hat.
Answer: No
- Queen asks third wise woman: Do you know the color of your hat?
- What is her answer?

Motivation

Reasoning about knowledge

We saw that KT45 can be used to reason about an agent's knowledge.

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We have three agents (queen does not count), not just one. We want them to be able to reason about *each others* knowledge.

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Idea

Introduce a \Box operator for each agent, and a \Box operator for a group of agents.

Modal Logic KT45ⁿ

Agents

Assume a set $\mathcal{A} = \{1, 2, \dots, n\}$ of agents.

Modal Logic KT45^n

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Modal connectives

Replace \Box by:

- K_i for each agent i
- E_G for any subset G of \mathcal{A}

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Example

$K_1 p \wedge K_1 \neg K_2 K_1 p$ means:

Agent 1 knows p , and also that Agent 2 does not know that Agent 1 knows p .

Common Knowledge

“Everyone knows that everyone knows”

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Common knowledge

The infinite conjunction $E_G \phi \wedge E_G E_G \phi \wedge \dots$ is called “common knowledge of ϕ ”, denoted, $C_G \phi$.

Distributed Knowledge

Combine knowledge

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The operator $D_G\phi$ is called “distributed knowledge of ϕ ”, denoted, $D_G \phi$.

Models of KT45^n

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- 3 A labeling function $L : W \rightarrow \mathcal{P}(\text{Atoms})$.

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Take a model $\mathcal{M} = (W, (R_i)_{i \in \mathcal{A}}, L)$ and a world $x \in W$. We define $x \Vdash \phi$ via structural induction:

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- $x \Vdash \phi \vee \psi$ iff $x \Vdash \phi$ or $x \Vdash \psi$
- $x \Vdash \phi \rightarrow \psi$ iff $x \Vdash \psi$, whenever $x \Vdash \phi$
- ...

Semantics of $KT45^n$ (continued)

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Semantics of KT45^n (continued)

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Take a model $\mathcal{M} = (W, (R_i)_{i \in \mathcal{A}}, L)$ and a world $x \in W$. We define $x \Vdash \phi$ via structural induction:

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- $x \Vdash K_i \phi$ iff for each $y \in W$ with $R_i(x, y)$, we have $y \Vdash \phi$
- $x \Vdash E_G \phi$ iff for each $i \in G$, $x \Vdash K_i \phi$.

Semantics of $KT45^n$ (continued)

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Take a model $\mathcal{M} = (W, (R_i)_{i \in \mathcal{A}}, L)$ and a world $x \in W$. We define $x \Vdash \phi$ via structural induction:

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- $x \Vdash K_i \phi$ iff for each $y \in W$ with $R_i(x, y)$, we have $y \Vdash \phi$
- $x \Vdash E_G \phi$ iff for each $i \in G$, $x \Vdash K_i \phi$.
- $x \Vdash C_G \phi$ iff for each $k \geq 1$, we have $x \Vdash E_G^k \phi$.

Semantics of $KT45^n$ (continued)

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Take a model $\mathcal{M} = (W, (R_i)_{i \in \mathcal{A}}, L)$ and a world $x \in W$. We define $x \Vdash \phi$ via structural induction:

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- $x \Vdash K_i \phi$ iff for each $y \in W$ with $R_i(x, y)$, we have $y \Vdash \phi$
- $x \Vdash E_G \phi$ iff for each $i \in G$, $x \Vdash K_i \phi$.
- $x \Vdash C_G \phi$ iff for each $k \geq 1$, we have $x \Vdash E_G^k \phi$.
- $x \Vdash D_G \phi$ iff for each $y \in W$, we have $y \Vdash \phi$, whenever $R_i(x, y)$ for all $i \in G$.

Formulation of Wise-Women Puzzle

Setup

- Wise woman i has red hat: p_i
- Wise woman i knows that wise woman j has a red hat:
 $K_i p_j$

Formulation of Wise-Women Puzzle

Initial situation

$$\begin{aligned}\Gamma = \{ & C(p_1 \vee p_2 \vee p_3), \\ & C(p_1 \rightarrow K_2 p_1), C(\neg p_1 \rightarrow K_2 \neg p_1), \\ & C(p_1 \rightarrow K_3 p_1), C(\neg p_1 \rightarrow K_3 \neg p_1), \\ & C(p_2 \rightarrow K_1 p_2), C(\neg p_2 \rightarrow K_1 \neg p_2), \\ & C(p_2 \rightarrow K_3 p_2), C(\neg p_2 \rightarrow K_3 \neg p_2), \\ & C(p_3 \rightarrow K_1 p_3), C(\neg p_2 \rightarrow K_1 \neg p_3), \\ & C(p_3 \rightarrow K_2 p_3), C(\neg p_2 \rightarrow K_2 \neg p_3)\}\end{aligned}$$

Announcements

First wise woman says “No”

$$C(\neg K_1 p_1 \wedge \neg K_1 \neg p_1)$$

Second wise woman says “No”

$$C(\neg K_2 p_2 \wedge \neg K_2 \neg p_2)$$

First Attempt

$$\Gamma, C(\neg K_1 p_1 \wedge \neg K_1 \neg p_1), C(\neg K_2 p_2 \wedge \neg K_2 \neg p_2) \vdash K_3 p_3$$

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Problem

This does not take time into account. The second announcement can take the first announcement into account.

Solution

Prove separately:

Entailment 1 :

$$\Gamma, C(\neg K_1 p_1 \wedge \neg K_1 \neg p_1) \vdash C(p_2 \vee p_3)$$

Solution

Prove separately:

Entailment 1 :

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Entailment 2 :

$$\Gamma, C(p_2 \vee p_3), C(\neg K_2 p_2 \wedge \neg K_2 \neg p_2) \vdash K_3 p_3$$

Solution

Prove separately:

Entailment 1 :

$$\Gamma, C(\neg K_1 p_1 \wedge \neg K_1 \neg p_1) \vdash C(p_2 \vee p_3)$$

Entailment 2 :

$$\Gamma, C(p_2 \vee p_3), C(\neg K_2 p_2 \wedge \neg K_2 \neg p_2) \vdash K_3 p_3$$

Proof

Through natural deduction in KT45ⁿ.